iPad Link to Drones Feed

* Create in Python first and see if can transfer to C++ later.
* Input from camera goes into Jetson and gets annotated. This annotated data must go from Jetson into HM30 on drone.
* HM30 sends real-time annotated footage to iPad via wireless connection. This uses a RTSP stream with OpenCV.
* Most likely uses G-Streamer and OpenCV. Must be RTSP Stream. In .265 video format.

Information

* <https://discuss.ardupilot.org/t/connecting-siyi-hm30-with-jetson-nano/110457/27?page=2>
* <https://discuss.ardupilot.org/t/connecting-siyi-hm30-with-jetson-nano/110457/19>
* Technically the Nano could be set to SIYI standard address in order to read and retransmit video  
  IN: SIYI AI Camera: rtsp://192.168.144.60/video1  
  OUT: Main Stream: rtsp://192.168.144.25:8554/video1  
  That would require an Ethernet switch as the Nano is a single Ethernet Port
* gstreamer pipeline from Jetson Nano to Air Unit that can be invoked from terminal or within image processing like OpenCV
* <https://www.reddit.com/r/computervision/comments/n5g3bl/rtsp_camera_for_jetson_nano_andor_xavier/>